



47. Course Specification of Electrical Drives

I. Course Identification and General Information:					
1.	Course Title:	Electrical Drives			
2.	Course Code & Number:	PME327			
3.	Credit hours:	C.H			Total
		Th.	Tu.	Pr.	
		2	2	2	-
4.	Study level/ semester at which this course is offered:	Fourth Year/ Second Semester			
5.	Pre –requisite (if any):	PME221, PME224, PME244			
6.	Co –requisite (if any):	None.			
7.	Program (s) in which the course is offered:	Electrical Power and Machines Engineering			
8.	Language of teaching the course:	English			
9.	Location of teaching the course:	Class & lab			
10.	Prepared By:	Assoc. Prof. Dr. Radwan Al bouthigy			
11.	Date of Approval	2020			

II. Course Description:
<p>Electrical drives circuits are a subject where a student will deal with various types of electric drives machines which are employed in industries, power stations, domestic and commercial appliances etc. It gives students the skills in the definitions, analysis, and solving problems related to electric variable speed drive. The course enables students to analyzes and discuss the basic characteristics, types, operating modes of DC motors, induction motor, synchronous motor, stepper motor and theirs methods speed control with special emphasis on Computer simulations are used for understanding electric drives-based power-electronics converters and the design of feedback controllers. Laboratory experiments and MATLAB simulation tool are carried out for different types of power electronics elements to verify the theoretical concepts.</p>

III. Course Intended learning outcomes (CILOs) of the course	Referenced PILOs
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a1	Demonstrate the mechanical system requirements for electric drives and the switch -mode power electronic converters in electric drives	A1
a2	Define the dynamic modeling of Induction motor drive, volt - hertz, vector control and speed control of synchronous motors.	A2
b1	Identify the DC-motor drives, electronically-commutated motor drives and energy efficiency of electric drives and inverter-motor interactions.	B1
b2	Differentiate between different AC/DC drive for solving engineering problems and selection the appropriate solution according to needed specification.	B3
c1	Apply a variety of device models and circuit analysis theorems to analysis, design and implementing power control systems for engineering systems applications.	C2
c2	Carry out practical hands-on work in the field.	C3
d1	Work in teams to conduct experiments, analyze results, and develop technically sound reports of outcomes.	D1
d2	Use computer and Internet to extract information related to field of study.	D2, D5

(A) Alignment Course Intended Learning Outcomes of Knowledge and Understanding to Teaching Strategies and Assessment Strategies:

Course Intended Learning Outcomes	Teaching strategies	Assessment Strategies
a1- Demonstrate an understanding the mechanical system requirement for electric drives and the switch - mode power electronic converters in electric drives	<ul style="list-style-type: none"> ▪ Lectures ▪ Tutorials ▪ Self-learning ▪ Dialogue and discussion 	<ul style="list-style-type: none"> ▪ written exam ▪ Oral discussion ▪ Reports evaluation ▪ Presentations and evaluation
a2- Define the dynamic modeling of Induction motor drive, volt - hertz, vector control and speed control of synchronous motors.	<ul style="list-style-type: none"> ▪ Lectures ▪ Tutorials ▪ Self-learning ▪ Dialogue and discussion 	<ul style="list-style-type: none"> ▪ written exam ▪ Oral discussion ▪ Reports evaluation ▪ Presentations and evaluation

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(B) Alignment Course Intended Learning Outcomes of Intellectual Skills to Teaching Strategies and Assessment Strategies:		
Course Intended Learning Outcomes	Teaching strategies	Assessment Strategies
b1- Identify the DC-motor drives, electronically-commutated motor drives and energy efficiency of electric drives and inverter-motor interactions.	<ul style="list-style-type: none"> ▪ Lectures ▪ Analysis and Problem solving ▪ Tutorials ▪ Project 	<ul style="list-style-type: none"> ▪ Written Test and Quizzes ▪ Laboratory reports evaluation ▪ Project reports ▪ Presentations
b2- Differentiate between different AC/DC drive for solving engineering problems and selection the appropriate solution according to needed specification.	<ul style="list-style-type: none"> ▪ Lectures ▪ Analysis and Problem solving ▪ Tutorials ▪ Project 	<ul style="list-style-type: none"> ▪ Written Test and Quizzes ▪ Laboratory reports evaluation ▪ Project reports ▪ Presentations

© Alignment Course Intended Learning Outcomes of Professional and Practical Skills to Teaching Strategies and Assessment Strategies:		
Course Intended Learning Outcomes	Teaching strategies	Assessment Strategies
c1- Apply a variety of device models and circuit analysis theorems to analysis, design and implementing power control systems for engineering systems applications.	<ul style="list-style-type: none"> ▪ Lectures ▪ Laboratory ▪ Projects ▪ Design exercises ▪ Simulation tools 	<ul style="list-style-type: none"> ▪ Written Test and Quizzes ▪ Laboratory reports evaluation ▪ Presentations evaluation ▪ Project reports ▪ Observation of performance
c2- Carry out practical hands-on work in the field.	<ul style="list-style-type: none"> ▪ Lectures ▪ Laboratory ▪ Projects ▪ Design exercises ▪ Simulation tools 	<ul style="list-style-type: none"> ▪ Written Test and Quizzes ▪ Laboratory reports evaluation ▪ Presentations evaluation ▪ Project reports ▪ Observation of performance

(D) Alignment Course Intended Learning Outcomes of Transferable Skills to Teaching Strategies and Assessment Strategies:

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Course Intended Learning Outcomes	Teaching strategies	Assessment Strategies
<p>d1- Work in teams to conduct experiments, analyze results, and develop technically sound reports of outcomes.</p>	<ul style="list-style-type: none"> ▪ Laboratory ▪ Projects ▪ Presentations ▪ Research 	<ul style="list-style-type: none"> ▪ Observation and interviews ▪ Laboratory reports evaluation ▪ Research reports ▪ Presentations
<p>d2- Use computer and Internet to extract information related to field of study.</p>	<ul style="list-style-type: none"> ▪ Laboratory ▪ Projects ▪ Presentations ▪ Research 	<ul style="list-style-type: none"> ▪ Observation and interviews ▪ Laboratory reports evaluation ▪ Research reports ▪ Presentations

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IV. Course Content:					
A – Theoretical Aspect:					
Order	Units/Topics List	Learning Outcomes	Sub Topics List	Number of Weeks	Contact hours
1.	Introduction of Drives	a1,a2,b1,b2	<ul style="list-style-type: none"> ▪ Basic characteristics and operating modes of DC Motor Drives ▪ Performance characteristics of Induction Motor ▪ Performance characteristics Synchronous motors ▪ Stepper motor 	2	4
2.	DC drives	a1, b1, c1,c2,d2	<ul style="list-style-type: none"> ▪ Single phase drives ▪ Three phase drive ▪ Chopper drives ▪ Closed loop control of DC motor 	4	8
3.	Induction motor drives	b1,b2,c1,c2,d2	<ul style="list-style-type: none"> ▪ Stator voltage control ▪ Rotor voltage control ▪ Frequency control ▪ Voltage frequency control ▪ Current control ▪ Voltage, current and frequency control ▪ Closed loop control of induction motor 	4	8
4.	Vector control	a1, b1,b2,c1,d2	<ul style="list-style-type: none"> ▪ Basic Principle of Vector Control ▪ Direct and Quadrature-Axis Transformation ▪ Indirect Vector Control ▪ Direct Vector Control 	1	2

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5.	Synchronous motor drives	a2, b2,c1,c2,d2	<ul style="list-style-type: none"> ▪ Cylindrical rotor motors ▪ Salient pole motors ▪ Reluctance motors ▪ Permanent magnetic motors ▪ Switched reluctance motors ▪ Closed loop control of synchronous motor 	2	4
6.	Stepper motor drives	b1,b2,c1,c2,d2	<ul style="list-style-type: none"> ▪ Stepper motor control ▪ Variable Reluctance stepper motors ▪ Permanent Magnetic stepper motors 	1	2
Number of Weeks /and Units Per Semester				14	28

B- Tutorial Aspect:				
Order	Tasks/ Tutorial	No. of Weeks	Contact Hours	Learning Outcomes
1.	<ul style="list-style-type: none"> ▪ Operation and c Basic Characteristics of Dc Motors ▪ Operating Modes of Separately Excited Dc Motor ▪ Operating Modes of Series Excited Dc Motor 	1	2	a1,b1,d1,d2
2.	<ul style="list-style-type: none"> ▪ Operation and characteristics of Single-Phase Semi converter Drives. ▪ Operation and characteristics of Single-Phase Full-Converter Drives ▪ Operation and characteristics of Single-Phase Dual-Converter Drives ▪ Simulating single phase drives by using MATLAB 	2	4	a1,a2,b1,b2, d1,d2
3.	<ul style="list-style-type: none"> ▪ Operation and characteristics of three-Phase Semi converter Drives. 	2	4	a1,a2,b1,b2, c1,d1,d2

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	<ul style="list-style-type: none"> ▪ Operation and characteristics of three-Phase Full-Converter Drives ▪ Operation and characteristics of three-Phase Dual-Converter Drives ▪ Simulating three phase drives by using MATLAB 			
4.	<ul style="list-style-type: none"> ▪ Principle of Power Control ▪ Principle of Regenerative Brake Control ▪ Principle of Rheostatic Brake Control ▪ Principle of Combined Regenerative and Rheostatic Brake control ▪ Two- and Four-Quadrant Dc–dc Converter Drives ▪ Open-Loop Transfer Function of Separately Excited motors ▪ Open-Loop Transfer Function of Series Excited Motors ▪ Closed-Loop Transfer Function ▪ Simulating DC-DC drives by using MATLAB 	2	4	b1,b2,c1,d1,d2
5.	<ul style="list-style-type: none"> ▪ Performance Characteristics of induction motors ▪ Torque–Speed Characteristics ▪ Stator Voltage Control ▪ Rotor Voltage Control ▪ Frequency Control ▪ Voltage and Frequency Control 789 ▪ Current Control ▪ Constant Slip-Speed Control ▪ Voltage, Current, and Frequency Control ▪ Closed-Loop Control of Induction Motors ▪ Simulating induction motors drives by using MATLAB 	3	6	a1,a2, c1,d1,d2
6.	<ul style="list-style-type: none"> ▪ Basic Principle of Vector Control 	1	2	a1,a2,b1,b2,c1

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	<ul style="list-style-type: none"> Operation of Direct and Quadrature-Axis Transformation Operation of Indirect Vector Control Operation of Direct Vector Control 			
7.	<ul style="list-style-type: none"> Control characteristics of synchronous motor and the methods for speed control Simulating ac synchronous motor using MATLAB 	2	4	b1,b2,c1,d1,d2
8.	<ul style="list-style-type: none"> Control characteristics of Variable-Reluctance Stepper Motors Control characteristics of Permanent-Magnet Stepper Motors 	1	2	a2,b1,c1,d1,d2
Number of Weeks /and Units Per Semester:		14	28	

C - Practical Aspect:				
Order	Tasks/ Experiments	Number of Weeks	Contact hours	Learning Outcomes
1.	Single phase semi converter drive	1	2	a1,b1,c1,c2
2.	Single phase full wave converter drive	1	2	a1,b1,c1,c2,d1,d2
3.	Single phase dual converter drive	1	2	b1,b2,c1,c2,d1,d2
4.	Three phase half wave converter drive	1	2	a1,a2,b1,b2,c1,c2,d1,d2
5.	Three phase semi converter drive	2	4	a1,a2,b1,b2,c1,c2
6.	Three phase full wave converter drive	2	4	b1,b2,c1,c2,d1,d2
7.	Power control drive	1	2	a1,a2,b1,b2,c1,c2, d2
8.	Regenerative brake control	1	2	a1,a2,b1,b2,c1,c2,d1
9.	Induction motors control used AC voltage control	1	2	a1,a2,b2,c1,c2,d1,d2

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10.	▪ Induction motors control used inverters	1	2	a1, b2,c1,c2,d1,d2
11.	▪ Slip power control of wound rotor induction motors	1	2	a1,a2,b2,c1,c2
12.	▪ Review	1	2	a1,a2,b1,b2,c1,c2
Number of Weeks /and Units Per Semester		14	28	

V. Teaching strategies of the course:				
<ul style="list-style-type: none"> ▪ Lectures ▪ Problem Solving ▪ Design exercises ▪ Laboratory works ▪ Homework ▪ Project work ▪ Simulation Tools ▪ Presentations 				

VI. Assignments:				
No	Assignments	Aligned CILOs(symbols)	Week Due	Mark
1.	Comparison between types of modes operation	a1,a2,b1,b2,d2	3 rd	4
2.	Design and implementation of power control circuits using MATLAB tools	a1,a2,b1,b2,c1	4 th	4
3.	Design and implementation of dynamic brake control circuits using MATLAB tools	a1,a2,b1,b2,c1	6 th	4
4.	Design and implementation of closed loop control of S.E.D.C. motor circuits using MATLAB tools	a1,a2,b1,b2,c1	8 th	4
5.	Design and implementation of volt- hertz control of induction motor using MATLAB tools	a1,a2,b1,b2,c1	10 th	4
Total				20

VII. Schedule of Assessment Tasks for Students During the Semester:

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No.	Assessment Method	Week Due	Mark	Proportion of Final Assessment	Aligned Course Learning Outcomes
1.	Quizzes	4 th , 7 th , 10 th , and 13 th	20	10%	a1,a2,b1,b2
2.	Assignments	Weekly	20	10%	a1,a2,b1,b2,c1,d1
3.	Mid-Term exam	7 th	20	10%	a1,a2,b1,b2
4.	Final exam practical	15 th	40	20%	a1,a2,b1,b2,c1,c2
5.	Final Exam theory	16 th	100	50%	a1,a2,b1,b2
Total			200	100%	

VIII. Learning Resources:	
<ul style="list-style-type: none"> Written in the following order: (Author - Year of publication – Title – Edition – Place of publication – Publisher). 	
1- Required Textbook(s) (maximum two).	
	<ol style="list-style-type: none"> 1.M. H. Rashid, 2014, “Power electronics: circuits, devices, and applications,” fourth edition, Prentice Hall 2.Austin Hughes, (2006) Electric Motors and Drives Fundamentals, Types and Applications, 3rd Edition, Elsevier Ltd.
2- Essential References.	
	<ol style="list-style-type: none"> 1. Cyril W. Lander, 1993, “Power electronics”, 3rd edition, McGraw-Hill. 2. B. W. Williams, 1992, Power Electronics, Devices, Drivers, Application and Passive components 3. Fang Lin Luo, Hong Ye, Muhammad Rashid, "Digital Power Electronics and Applications", 2005, Elsev USA 4. E. Acha, Power Electronics control in Electrical system, 1st , 2002, Newnes.
3- Electronic Materials and Web Sites etc.	
	<ol style="list-style-type: none"> 1. www.goelectricdrive.com/ 2. www.electricmachinery.com/ 3. www.goelectricdrive.com/

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4. <http://www.ece.tamu.edu/~empelab/>

IX. Course Policies:	
1.	Class Attendance: A student should attend not less than 75 % of total hours of the subject; otherwise he will not be able to take the exam and will be considered as exam failure. If the student is absent due to illness, he/she should bring an approved statement from university Clinic
2.	Tardy: For late in attending the class, the student will be initially notified. If he repeated lateness in attending class he will be considered as absent.
3.	Exam Attendance/Punctuality: A student should attend the exam on time. He is Permitted to attend an exam half one hour from exam beginning, after that he/she will not be permitted to take the exam and he/she will be considered as absent in exam-
4.	Assignments & Projects: The assignment is given to the students after each chapter; the student has to submit all the assignments for checking on time-
5.	Cheating: For cheating in exam, a student will be considered as fail. In case the cheating is repeated three times during his/her study the student will be disengaged from the Faculty-
6.	Plagiarism: Plagiarism is the attending of a student the exam of a course instead of another student. If the examination committee proved a plagiarism of a student, he will be disengaged from the Faculty. The final disengagement of the student from the Faculty should be confirmed from the Student Council Affair of the university.
7.	Other policies: - Mobile phones are not allowed to use during a class lecture. It must be closed, otherwise the student will be asked to leave the lecture room - Mobile phones are not allowed in class during the examination. Lecture notes and assignments my given directly to students using soft or hard copy

Reviewed By	<u>Vice Dean for Academic Affairs and Post Graduate Studies: Asst. Prof. Dr. Tarek A. Barakat</u> <u>President of Quality Assurance Unit: Assoc. Prof. Dr. Mohammed Algorafi</u>
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	<u>Deputy Rector for Academic Affairs Asst. Prof. Dr. Ibrahim AlMutaa</u> <u>Assoc. Prof. Dr. Ahmed Mujahed</u> <u>Asst. Prof. Dr. Munasar Alsubri</u>

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47. Template for Course Plan of Electrical Drives

I. Information about Faculty Member Responsible for the Course:							
Name of Faculty Member	Assoc. Prof. Dr. Radwan Al bouthigy	Office Hours					
Location & Telephone No.	775284933	SAT	SUN	MON	TUE	WED	THU
E-mail	radwan006@yahoo.com						

II. Course Identification and General Information:						
1.	Course Title:	Electrical Drives				
2.	Course Number & Code:	PME327				
3.	Credit hours:	C.H				Total
		Th.	Tu.	Pr.	Tr.	
		2	2	2	-	4
4.	Study level/year at which this course is offered:	Fourth Year/ Second Semester				
5.	Pre –requisite (if any):	PME221, PME224, PME244				
6.	Co –requisite (if any):	NA				
7.	Program (s) in which the course is offered	POWER & Machines program				
8.	Language of teaching the course:	English				
9.	System of Study:	Semester				
10.	Mode of delivery:	semester				
11.	Location of teaching the course:	Class & lab				

III. Course Description:
<p>Electrical drives circuits are a subject where a student will deal with various types of electric drives machines which are employed in industries, power stations, domestic and commercial appliances etc. It gives students the skills in the definitions, analysis, and solving problems related to electric variable speed drive. The course enables students to analyzes and discuss the basic characteristics, types, operating modes of DC motors, induction motor, synchronous</p>

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motor, stepper motor and their methods speed control with special emphasis on Computer simulations are used for understanding electric drives-based power-electronics converters and the design of feedback controllers. Laboratory experiments and MATLAB simulation tool are carried for different types of power electronics elements to verify the theoretical concepts.

IV. Intended learning outcomes (ILOs) of the course:

- Brief summary of the knowledge or skill the course is intended to develop:
1. Demonstrate the mechanical system requirements for electric drives and the switch - mode power electronic converters in electric drives
 2. Define the dynamic modeling of Induction motor drive, volt - hertz, vector control and speed control of synchronous motors.
 3. Identify the DC-motor drives, electronically-commutated motor drives and energy efficiency of electric drives and inverter-motor interactions.
 4. Differentiate between different AC/DC drive for solving engineering problems and selection the appropriate solution according to needed specification.
 5. Apply a variety of device models and circuit analysis theorems to analysis, design and implementing power control systems for engineering systems applications.
 6. Carry out practical hands-on work in the field.
 7. Work in teams to conduct experiments, analyze results, and develop technically sound reports of outcomes.
 8. Use computer and Internet to extract information related to field of study.

V. Course Content:

A – Theoretical Aspect:				
Order	Units/Topics List	Sub Topics List	Number of Weeks	Contact hours
1.	Introduction of Drives	<ul style="list-style-type: none"> ▪ Basic characteristics and operating modes of DC Motor Drives ▪ Performance characteristics of Induction Motor ▪ Performance characteristics Synchronous motors ▪ Stepper motor 	1 st ,2 nd	4

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2.	DC drives	<ul style="list-style-type: none"> ▪ Single phase drives ▪ Three phase drive ▪ Chopper drives ▪ Closed loop control of DC motor 	3 rd , 4 th , 5 th , 6 th	8
3.	Midterm exam		7 th	2
4.	Induction motor drives	<ul style="list-style-type: none"> ▪ Stator voltage control ▪ Rotor voltage control ▪ Frequency control ▪ Voltage frequency control ▪ Current control ▪ Voltage, current and frequency control ▪ Closed loop control of induction motor 	8 th , 9 th , 10 th , 11 th	8
5.	Vector control	<ul style="list-style-type: none"> ▪ Basic Principle of Vector Control ▪ Direct and Quadrature-Axis Transformation ▪ Indirect Vector Control ▪ Direct Vector Control 	12 th	2
6.	Synchronous motor drives	<ul style="list-style-type: none"> ▪ Cylindrical rotor motors ▪ Salient pole motors ▪ Reluctance motors ▪ Permanent magnetic motors ▪ Switched reluctance motors ▪ Closed loop control of synchronous motor 	13 th , 14 th	4
7.	Stepper motor drives	<ul style="list-style-type: none"> ▪ Stepper motor control ▪ Variable Reluctance stepper motors ▪ Permanent Magnetic stepper motors 	15 th	2
8.	Final exam	<ul style="list-style-type: none"> ▪ All topics 	16 th	2
Number of Weeks /and Units Per Semester			16	32

B- Tutorial Aspect:			
Order	Tasks/ Tutorial	No. of Weeks	Contact Hours
1.	<ul style="list-style-type: none"> ▪ Operation and c Basic Characteristics of Dc Motors ▪ Operating Modes of Separately Excited Dc Motor ▪ Operating Modes of Series Excited Dc Motor 	1 st	2

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2.	<ul style="list-style-type: none"> ▪ Operation and characteristics of Single-Phase Semi converter Drives. ▪ Operation and characteristics of Single-Phase Full-Converter Drives ▪ Operation and characteristics of Single-Phase Dual-Converter Drives ▪ Simulating single phase drives by using MATLAB 	2 nd ,3 rd	4
3.	<ul style="list-style-type: none"> ▪ Operation and characteristics of three-Phase Semi converter Drives. ▪ Operation and characteristics of three-Phase Full-Converter Drives ▪ Operation and characteristics of three-Phase Dual-Converter Drives ▪ Simulating three phase drives by using MATLAB 	4 th ,5 th	4
4.	<ul style="list-style-type: none"> ▪ Principle of Power Control ▪ Principle of Regenerative Brake Control ▪ Principle of Rheostatic Brake Control ▪ Principle of Combined Regenerative and Rheostatic Brake control ▪ Two- and Four-Quadrant Dc–dc Converter Drives ▪ Open-Loop Transfer Function of Separately Excited motors ▪ Open-Loop Transfer Function of Series Excited Motors ▪ Closed-Loop Transfer Function ▪ Simulating DC-DC drives by using MATLAB 	6 th ,7 th	4
5.	<ul style="list-style-type: none"> ▪ Performance Characteristics of induction motors ▪ Torque–Speed Characteristics ▪ Stator Voltage Control ▪ Rotor Voltage Control ▪ Frequency Control ▪ Voltage and Frequency Control 789 ▪ Current Control ▪ Constant Slip-Speed Control ▪ Voltage, Current, and Frequency Control ▪ Closed-Loop Control of Induction Motors ▪ Simulating induction motors drives by using MATLAB 	8 th ,9 th ,10 th	6
6.	<ul style="list-style-type: none"> ▪ Basic Principle of Vector Control ▪ Operation of Direct and Quadrature-Axis Transformation 	11 th	2

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 Prof. Dr. Mohammed AL-Bukhaiti

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	<ul style="list-style-type: none"> ▪ Operation of Indirect Vector Control ▪ Operation of Direct Vector Control 		
7.	<ul style="list-style-type: none"> ▪ Control characteristics of synchronous motor and the methods for speed control ▪ Simulating ac synchronous motor using MATLAB 	12 th , 13 th	4
8.	<ul style="list-style-type: none"> ▪ Control characteristics of Variable-Reluctance Stepper Motors ▪ Control characteristics of Permanent-Magnet Stepper Motors 	14 th	2
Number of Weeks /and Units Per Semester:		14	28

C - Practical Aspect:			
Order	Tasks/ Experiments	Number of Weeks	Contact hours
1.	▪ Single phase semi converter drive	1 st	2
2.	▪ Single phase full wave converter drive	2 nd	2
3.	▪ Single phase dual converter drive	3 rd	2
4.	▪ Three phase half wave converter drive	4 th	2
5.	▪ Three phase semi converter drive	5 th , 6 th	4
6.	▪ Three phase full wave converter drive	7 th , 8 th	4
7.	▪ Power control drive	9 th	2
8.	▪ Regenerative brake control	10 th	2
9.	▪ Induction motors control used AC voltage control	11 th	2
10.	▪ Induction motors control used inverters	12 th	2
11.	▪ Slip power control of wound rotor induction motors	13 th	2
12.	▪ Review	14 th	2
Number of Weeks /and Units Per Semester		14	28

VI. Teaching strategies of the course:
<ul style="list-style-type: none"> ▪ Lectures ▪ Problem Solving ▪ Design exercises

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- Laboratory works
- Homework
- Project work
- Simulation Tools
- Presentations

VII. Assignments:				
No	Assignments	Aligned CILOs(symbols)	Week Due	Mark
1.	Comparison between types of modes operation	a1,a2,b1,b2,d2	3 rd	4
2.	Design and implementation of power control circuits using MATLAB tools	a1,a2,b1,b2,c1	4 th	4
3.	Design and implementation of dynamic brake control circuits using MATLAB tools	a1,a2,b1,b2,c1	6 th	4
4.	Design and implementation of closed loop control of S.E.D.C. motor circuits using MATLAB tools	a1,a2,b1,b2,c1	8 th	4
5.	Design and implementation of volt- hertz control of induction motor using MATLAB tools	a1,a2,b1,b2,c1	10 th	4
Total				20

VIII. Schedule of Assessment Tasks for Students During the Semester:				
No.	Assessment Method	Week Due	Mark	Proportion of Final Assessment
1.	Quizzes	4 th ,7 th ,10 th , and 13 th	20	10%
2.	Assignments	Weekly	20	10%
3.	Mid-Term exam	7 th	20	10%
4.	Final exam practical	15 th	40	20%
5.	Final Exam theory	16 th	100	50%
Total			200	100%

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IX. Learning Resources:	
<ul style="list-style-type: none"> Written in the following order: (Author - Year of publication – Title – Edition – Place of publication – Publisher). 	
1- Required Textbook(s) (maximum two).	
	<ol style="list-style-type: none"> M. H. Rashid, 2014, “Power electronics: circuits, devices, and applications,” fourth edition, Prentice Hall Austin Hughes, (2006) Electric Motors and Drives Fundamentals, Types and Applications, 3rd Edition, Elsevier Ltd.
2- Essential References.	
	<ol style="list-style-type: none"> Cyril W. Lander, 1993, “Power electronics”, 3rd edition, McGraw-Hill. B. W. Williams, 1992, Power Electronics, Devices, Drivers, Application and Passive components Fang Lin Luo, Hong Ye, Muhammad Rashid, "Digital Power Electronics and Applications", 2005, Elsev USA E. Acha, Power Electronics control in Electrical system, 1st , 2002, Newnes.
3- Electronic Materials and Web Sites etc.	
	<ol style="list-style-type: none"> www.goelectricdrive.com/ www.electricmachinery.com/ www.goelectricdrive.com/ http://www.ece.tamu.edu/~empelab/

X. Course Policies:	
1.	<p>Class Attendance: A student should attend not less than 75 % of total hours of the subject; otherwise he will not be able to take the exam and will be considered as exam failure. If the student is absent due to illness, he/she should bring an approved statement from university Clinic</p>
2.	<p>Tardy: For late in attending the class, the student will be initially notified. If he repeated lateness in attending class he will be considered as absent.</p>
3.	<p>Exam Attendance/Punctuality: A student should attend the exam on time. He is Permitted to attend an exam half one hour from exam beginning, after that he/she will not be permitted to take the exam and he/she will be considered as absent in exam-</p>
4.	<p>Assignments & Projects:</p>

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	The assignment is given to the students after each chapter; the student has to submit all the assignments for checking on time-
5.	Cheating: For cheating in exam, a student will be considered as failure . In case the cheating is repeated three times during his/her study the student will be disengaged from the Faculty-
6.	Plagiarism: Plagiarism is the attending of a student the exam of a course instead of another student. If the examination committee proved a plagiarism of a student, he will be disengaged from the Faculty. The final disengagement of the student from the Faculty should be confirmed from the Student Council Affair of the university.
7.	Other policies: - Mobile phones are not allowed to use during a class lecture. It must be closed, otherwise the student will be asked to leave the lecture room - Mobile phones are not allowed in class during the examination. Lecture notes and assignments my given directly to students using soft or hard copy

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Sana'a University
Faculty of Engineering
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