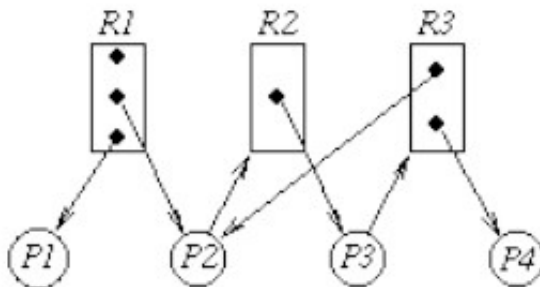




قائمة الاسئلة

202502261600_2_[CSY]_[Operating System]_[غراب موسى د.]

- 1) Which one is the Computer system components:
 - 1) - a. Operating system
 - 2) - b. Application programs
 - 3) - c. Users
 - 4) ☒ d. a, b and c are correct
- 2) Operating System characteristic:
 - 1) - a. control program
 - 2) - b. resource allocator
 - 3) - c. program that manages a computer's hardware
 - 4) ☒ d. a, b and c are correct
- 3) An amount of time a process has been waiting in the ready queue called
 - 1) - a. Average time
 - 2) ☒ b. Waiting time
 - 3) - c. Running time
 - 4) - d. a, b and c are not correct
- 4) The OS can be defined as
 - 1) - a. a control program
 - 2) - b. a resource allocator
 - 3) - c. program that manages a computer's hardware
 - 4) ☒ d. a, b and c are correct
- 5) Which one is a User interface.
 - 1) - a. Command-Line (CLI)
 - 2) - b. Graphics User Interface (GUI)
 - 3) - c. Batch
 - 4) ☒ d. a, b and c are correct
- 6) The job scheduling led to the concept known as the ____
 - 1) ☒ a. Multiprogramming
 - 2) - b. Job programming
 - 3) - c. Programming
 - 4) - d. Threading
- 7) In the following diagrams:



- 1) - a. There is deadlock start from P1
- 2) - b. There is deadlock in P1-R2-P2-R3
- 3) - c. There is no deadlock
- 4) ☒ d. a, b and c are not correct



- 8) Round robin is a
- 1) - Kind of magnetic drum
 - 2) - Memory allocation policy
 - 3) ☒ + Process scheduling policy
 - 4) - Process synchronization policy
- 9) which one is the type of System Calls:
- 1) - a. create file
 - 2) - b. read file
 - 3) - c. write file
 - 4) ☒ + d. a, b and c are correct
- 10) FIFO scheduling is
- 1) - Fair-share scheduling
 - 2) - Deadline scheduling
 - 3) ☒ + Non-preemptive scheduling
 - 4) - Preemptive scheduling
- 11) Which one is not as a process State
- 1) ☒ + Communicate
 - 2) - terminated
 - 3) - ready
 - 4) - waiting
- 12) Which one is not in Process Control Block (PCB)
- 1) - Program counter
 - 2) ☒ + bootstrap program
 - 3) - I/O status information
 - 4) - CPU registers
- 13) Consider the following set of processes with their Burst time and arrival time (table 1)

Table 1

| | Arrival Time | Burst Time |
|-----------|--------------|------------|
| P1 | 0 | 6 |
| P2 | 2 | 8 |
| P3 | 4 | 4 |
| P4 | 10 | 3 |

. The Gantt charts for the (SJF)

algorithm is:

- 1) - a. P3-P2-P4-P1
 - 2) - b. P1-P2-P3-P4
 - 3) - c. P4-P3-P2-P1
 - 4) ☒ + d. a, b and c are not correct
- 14) Consider the following set of processes with their Burst time (table 2)



Table 2

| <u>Process</u> | <u>Burst Time</u> |
|----------------|-------------------|
| P_1 | 6 |
| P_2 | 8 |
| P_3 | 7 |
| P_4 | 3 |

. From the table (2) the Gantt charts

for the (FCFS) algorithm

- 1) - a. P3-P2-P4-P1
 - 2) - b. P1-P2-P4-P3
 - 3) - c. P4-P3-P2-P1
 - 4) ☒ d. a, b and c are not correct
- 15) Consider the following set of processes with their Burst time (table 2)



Table 2

| <u>Process</u> | <u>Burst Time</u> |
|----------------|-------------------|
| P_1 | 6 |
| P_2 | 8 |
| P_3 | 7 |
| P_4 | 3 |

. From the table (2) the average

waiting time for the (SJF) is:

- 1) - 6.5
- 2) - 7.5
- 3) ☒ + 7
- 4) - all are false

16) Consider the following set of processes with their Burst time (table 2)



Table 2

| <u>Process</u> | <u>Burst Time</u> |
|----------------|-------------------|
| P_1 | 6 |
| P_2 | 8 |
| P_3 | 7 |
| P_4 | 3 |

. From the table (2) the average

waiting time for the (FCFS) is:

- 1) ☒ + 10.25
 - 2) ☐ - 10.5
 - 3) ☐ - 10
 - 4) ☐ - all are false
- 17) The state in which the process is waiting to be assigned to a processor is called
- 1) ☐ - a. waiting
 - 2) ☒ + b. ready
 - 3) ☐ - c. terminated
 - 4) ☐ - d. a, b and c are not correct
- 18) The information associated with each process is stored in
- 1) ☐ - a. Hard Disk
 - 2) ☐ - b. CPU
 - 3) ☒ + c. PCB
 - 4) ☐ - d. a, b and c are not correct
- 19) The operation when CPU switches to another process is called
- 1) ☐ - a. System call
 - 2) ☐ - b. Multiprocessing
 - 3) ☒ + c. context switch
 - 4) ☐ - d. a, b and c are not correct
- 20) Waiting time is :
- 1) ☐ - the total time in the blocked and waiting queue
 - 2) ☐ - the total time from the completion till the submission of a process
 - 3) ☒ + the total time spent in the ready queue
 - 4) ☐ - the total time spent in the running queue



21) Which of the following condition is required for deadlock to be possible?

- 1) - a. mutual exclusion
- 2) - b. Circular wait
- 3) - c. Hold and wait
- 4) ☒ d. a, b and c are correct

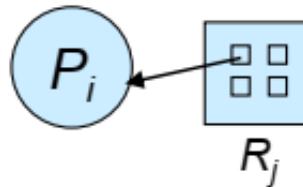
22) The _____ swaps processes in and out of the memory.

- 1) - CPU manager
- 2) ☒ memory manager
- 3) - user
- 4) - CPU

23) Scheduling leads to :

- 1) ☒ a. increase CPU utilization
- 2) - b. decrease CPU utilization
- 3) - c. keep the CPU more idle
- 4) - d. a, b and c are not correct

24)



in Resource-Allocation Graph the P_i process

- 1) - a. P_i requests instance of R_j
- 2) ☒ b. P_i is holding an instance of R_j
- 3) - c. P_i sends instance to R_j
- 4) - d. all the process are false

25) The following function is used to create a new process in Unix

- 1) - a. wait()
- 2) - b. exec ()
- 3) ☒ c. fork()
- 4) - d. None of the above are true

26) Which one of the following is the deadlock avoidance algorithm?

- 1) - a. round-robin algorithm
- 2) ☒ b. banker's algorithm
- 3) - c. elevator algorithm
- 4) - d. karn's algorithm

27) Threading Models

- 1) - a. One-to-One
- 2) - b. Many-to-One
- 3) - c. Many-to-Many
- 4) ☒ d. all the above are correct.

28) The Advantages of Multiprocessors system :

- 1) - a. Increased reliability
- 2) - b. Increased throughput
- 3) - c. Economy of scale
- 4) ☒ d. all a, b and c are correct

29) A process said to be in _____ state if it was waiting for an event that will never occur.

- 1) - Safe



- 2) ☒ Deadlock
- 3) ☐ Starvation
- 4) ☐ waiting
- 30) Starvation :
- 1) ☐ a. as time progresses increase the priority of the process
- 2) ☐ b. is priority scheduling where priority is the inverse of predicted next CPU burst time
- 3) ☒ c. low priority processes may never execute
- 4) ☐ d. a, b and c are not correct
- 31) what is an operating system?
- 1) ☐ type of computer hardware
- 2) ☒ a program that acts as an intermediary between a user and computer hardware
- 3) ☐ a software application for creating documents
- 4) ☐ an online service for storing data
- 32) "The one program running at all times on the computer" is the:
- 1) ☐ application
- 2) ☐ software
- 3) ☒ kernel
- 4) ☐ antivirus
- 33) What are system programs?
- 1) ☒ Programs that ship with the operating system but are not part of the kernel
- 2) ☐ All programs not associated with the operating system
- 3) ☐ Software frameworks providing additional services to developers
- 4) ☐ The one program running at all times on the computer
- 34) How does the operating system manage each device controller type?
- 1) ☐ Through direct user input
- 2) ☒ Using a device driver
- 3) ☐ Via a network connection
- 4) ☐ Through the CPU only
- 35) What is the difference between preemptive and nonpreemptive I/O ?
- 1) ☐ Preemptive I/O allows simultaneous processing of I/O requests, nonpreemptive does not
- 2) ☐ Nonpreemptive I/O allows the user program to continue without waiting for I/O completion
- 3) ☒ Preemptive I/O returns control to the user program without waiting for I/O completion, nonpreemptive I/O waits for completion
- 4) ☐ There is no difference mentioned
- 36) Device controller informs CPU that it has finished its operation by causing
- 1) ☐ bus
- 2) ☒ an interrupt
- 3) ☐ device driver
- 4) ☐ I/O devices
- 37) What is the primary distinction between a program and a process?
- 1) ☐ A program is active, while a process is passive
- 2) ☒ A program is passive, while a process is active
- 3) ☐ Both are active entities
- 4) ☐ Both are passive entities
- 38) In the abstract view of computer components, which of the following components interacts directly with the computer hardware?
- 1) ☐ User
- 2) ☐ Application programs
- 3) ☒ Operating system



- 4) - None of the above
- 39) What should the OS do for each type of error detected?
- 1) - Ignore the error if it's minor
 - 2) ☒ Take the appropriate action to ensure correct and consistent computing
 - 3) - Log the error and continue running
 - 4) - Restart the system
- 40) What is the purpose of logging in an operating system?
- 1) - To control user access to the system
 - 2) ☒ To keep track of which users use how much and what kinds of computer resources
 - 3) - To develop user interfaces
 - 4) - To enhance system security
- 41) What is one of the key differences between protection and security in a computer system?
- 1) ☒ Protection is about controlling access to resources, while security involves defending against external threats
 - 2) - Security is about controlling access to resources, while protection involves defending against external threats
 - 3) - Protection and security are the same concepts
 - 4) - Protection deals with user authentication only, while security deals with resource control
- 42) What is a system call?
- 1) - A method to start a computer
 - 2) ☒ A programming interface to the services provided by the OS
 - 3) - A type of network protocol
 - 4) - A way to format hard drives
- 43) What are the two types of goals in designing operating systems?
- 1) - Financial goals and marketing goals
 - 2) ☒ User goals and system goals
 - 3) - Design goals and implementation goals
 - 4) - Hardware goals and software goals
- 44) What is a benefit of using a higher-level language for OS implementation?
- 1) - It is always faster
 - 2) ☒ It is easier to port to other hardware
 - 3) - It requires less memory
 - 4) - It is more secure
- 45) What does a microkernel approach do?
- 1) - Moves as much as possible from user space into the kernel
 - 2) ☒ Moves as much as possible from the kernel into user space
 - 3) - Merges user space and kernel space
 - 4) - Eliminates user space entirely
- 46) How does the modular approach compare to the layered approach?
- 1) - It is less flexible
 - 2) ☒ It is similar but more flexible
 - 3) - It is more rigid
 - 4) - It is completely different and incompatible
- 47) The operating system is divided into a number of layers (levels). What is the bottom layer (layer 0)?
- 1) - User interface
 - 2) - Application programs
 - 3) ☒ Hardware
 - 4) - Network protocols
- 48) What is the difference between a program and a process?



- 1) ☒ A program is an executable file stored on disk, while a process is a program in execution
 - 2) ☐ A program is always active, while a process is stored on disk
 - 3) ☐ A program can run in parallel, while a process cannot
 - 4) ☐ A program is a task, while a process is a thread
- 49) What does the "Running" state of a process signify?
- 1) ☐ The process is being created
 - 2) ☐ The process is waiting for some event to occur
 - 3) ☒ Instructions are being executed
 - 4) ☐ The process has finished execution
- 50) How many processes can be running on any processor at any instant of time?
- 1) ☒ Only one
 - 2) ☐ Two
 - 3) ☐ Many
 - 4) ☐ None
- 51) What is each entry in the Process Table called?
- 1) ☐ Program Counter
 - 2) ☐ CPU Register
 - 3) ☒ Process Control Block (PCB)
 - 4) ☐ Memory Block
- 52) Which type of process spends more time doing computations with few very long CPU intervals?
- 1) ☐ I/O-bound process
 - 2) ☒ CPU-bound process
 - 3) ☐ Very-bound process
 - 4) ☐ Time-bound process
- 53) What is the goal of multiprogramming in process scheduling?
- 1) ☐ To run multiple processes in sequence
 - 2) ☒ To have some process running at all times to maximize CPU utilization
 - 3) ☐ To limit the number of processes in the system
 - 4) ☐ To prioritize I/O-bound processes
- 54) What is the device queue?
- 1) ☐ A set of all processes in the system
 - 2) ☐ A set of processes ready to execute
 - 3) ☒ A set of processes waiting for an I/O device
 - 4) ☐ A set of processes in the job queue
- 55) What does the short-term scheduler do?
- 1) ☐ Manages I/O devices
 - 2) ☒ Selects which process from the ready queue should be executed next
 - 3) ☐ Swaps processes in and out of memory
 - 4) ☐ Selects processes to be brought from mass storage into RAM
- 56) What happens if all processes are I/O-bound according to the long-term scheduler?
- 1) ☐ The CPU utilization is maximized
 - 2) ☒ The ready queue will almost always be empty, minimizing CPU utilization
 - 3) ☐ The I/O devices will be underutilized
 - 4) ☐ The memory usage is optimized
- 57) How can computation speedup be achieved in cooperating processes?
- 1) ☐ By executing tasks sequentially
 - 2) ☒ By breaking a task into subtasks and executing them in parallel
 - 3) ☐ By reducing the number of processes
 - 4) ☐ By using a single CPU for all tasks



- 58) What characteristic do most modern applications have?
- 1) - Single-threaded
 - 2) ☒ Multithreaded
 - 3) - Low-memory usage
 - 4) - High CPU usage
- 59) What are the benefits of using threads in an application?
- 1) - Decreased efficiency
 - 2) - Increased memory usage
 - 3) - Reduced CPU usage
 - 4) ☒ Increased efficiency
- 60) What is one benefit of using threads in terms of responsiveness?
- 1) - Threads reduce memory usage
 - 2) ☒ Threads may allow continued execution if part of a process is blocked
 - 3) - Threads increase the CPU speed
 - 4) - Threads eliminate the need for process synchronization
- 61) How do threads facilitate resource sharing?
- 1) - Threads use more memory than processes
 - 2) - Threads do not share any resources
 - 3) ☒ Threads share resources of a process, making it easier than shared memory or message passing
 - 4) - Threads use dedicated resources separate from processes
- 62) how is process creation described compared to thread creation?
- 1) - Both process and thread creation are heavy-weight
 - 2) - Both process and thread creation are light-weight
 - 3) ☒ Process creation is heavy-weight, while thread creation is light-weight
 - 4) - Process creation is light-weight, while thread creation is heavy-weight
- 63) Why are threads considered economical?
- 1) ☒ They are cheaper than process creation and have lower overhead than context switching
 - 2) - They are more expensive than processes
 - 3) - They have higher overhead than context switching
 - 4) - They do not use CPU resources
- 64) What is one of the challenges faced by programmers when working with multicore or multiprocessor systems?
- 1) - Increasing CPU speed
 - 2) ☒ Dividing activities
 - 3) - Reducing memory usage
 - 4) - Simplifying user interfaces
- 65) In the context of implicit threading, where does the biggest burden fall?
- 1) - On the operating system
 - 2) - On the hardware
 - 3) - On the programmers
 - 4) ☒ On the runtime library and the compiler
- 66) What is necessary to achieve maximum CPU utilization?
- 1) - Single-threaded processes
 - 2) ☒ Multiprogramming
 - 3) - Low-memory usage
 - 4) - High CPU usage
- 67) What is a CPU burst?
- 1) - The amount of time a process waits for input
 - 2) - The amount of time a process is stored in memory



- 3) ☒ + The amount of time a process uses the CPU until it starts waiting for some input or is interrupted
- 4) ☐ - The amount of time a process uses I/O resources
- 68) What happens during an I/O burst?
- 1) ☐ - The process performs computations
- 2) ☒ + The process waits for input or output operations to complete
- 3) ☐ - The process is terminated
- 4) ☐ - The process is stored in memory
- 69) In the context of preemptive scheduling, what does "preempted" mean?
- 1) ☐ - The process continues to run uninterrupted
- 2) ☐ - The process is terminated
- 3) ☒ + The process is temporarily halted to allow another process to run
- 4) ☐ - The process is moved to a different queue
- 70) In which situations is there no choice in terms of scheduling?
- 1) ☐ - When a process switches from running to ready state
- 2) ☐ - When a process switches from waiting to ready
- 3) ☐ - When a process switches from waiting state to running
- 4) ☒ + When a process is terminated or switches to waiting state
- 71) What can preemptive scheduling result in when data are shared among several processes?
- 1) ☐ - Deadlocks
- 2) ☒ + Race conditions
- 3) ☐ - Increased CPU utilization
- 4) ☐ - Decreased memory usage
- 72) In the context of the dispatcher, what does "switching context" involve?
- 1) ☐ - Changing the priority of a process
- 2) ☒ + Saving the state of the currently running process and restoring the state of the next process
- 3) ☐ - Allocating CPU time to the next process
- 4) ☐ - Terminating the currently running process
- 73) What is the main difference between preemptive and non-preemptive scheduling in the context of the short-term scheduler?
- 1) ☒ + Preemptive scheduling allows a process to be forcibly removed from the CPU, whereas non-preemptive scheduling does not.
- 2) ☐ - Non-preemptive scheduling allows a process to be forcibly removed from the CPU, whereas preemptive scheduling does not.
- 3) ☐ - Preemptive scheduling only occurs at system startup.
- 4) ☐ - Non-preemptive scheduling is used only for I/O-bound processes.
- 74) What is the primary distinction between kernel mode and user mode in an operating system?
- 1) ☐ - Kernel mode is for user-level applications, and user mode is for system-level operations.
- 2) ☒ + Kernel mode has unrestricted access to hardware, while user mode has restricted access.
- 3) ☐ - Kernel mode operates in a virtual environment, while user mode operates directly on hardware.
- 4) ☐ - There is no distinction between kernel mode and user mode.
- 75) What does a state-transition diagram represent in an operating system?
- 1) ☐ - The scheduling of threads
- 2) ☒ + The lifecycle of a process
- 3) ☐ - The allocation of memory
- 4) ☐ - The structure of the file system
- 76) Each process utilizes a resource as .
- 1) ☒ + request ,use , release
- 2) ☐ - use, release, request
- 3) ☐ - release, use, request



- 4) - request, release, use
- 77) Which of the following conditions must hold simultaneously for a deadlock to occur?
- 1) - Mutual Exclusion
 - 2) - Hold and Wait
 - 3) - No Preemption
 - 4) ☒ All
- 78) What does the "Hold and Wait" condition mean in the context of deadlocks?
- 1) - only one thread at a time can use a resource
 - 2) ☒ a thread holding at least one resource is waiting to acquire additional resources held by other threads
 - 3) - a resource can be released only voluntarily by the thread holding it, after that thread has completed its task
 - 4) - None of them
- 79) If a graph contains a cycle and all resources have only one instance then
- 1) - no deadlock
 - 2) - possibility deadlock
 - 3) ☒ deadlock
 - 4) - all false
- 80) deadlock prevention technique ensures that. If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
- 1) - Mutual exclusion
 - 2) - Hold and wait
 - 3) ☒ No preemption
 - 4) - Circular wait
- 81) In deadlock prevention: Invalidating the condition is most common.
- 1) - mutual exclusion
 - 2) - hold and wait
 - 3) - no preemption
 - 4) ☒ circular wait
- 82) Simplest and most useful model requires that each thread declare the maximum number of resources of each type that it may need
- 1) - deadlock prevention
 - 2) ☒ deadlock avoidance
 - 3) - deadlock detection
 - 4) - deadlock ignore
- 83) If a system is in unsafe state then...
- 1) - no deadlock
 - 2) - deadlock
 - 3) ☒ possibility deadlock
 - 4) - All of them are True
- 84)edge $T \rightarrow R$ indicated that process T may request resource R; represented by a dashed line
- 1) ☒ claim
 - 2) - request
 - 3) - assignment
 - 4) - None of them
- 85)Allow system to enter deadlock state
- 1) - deadlock prevention
 - 2) - deadlock avoidance
 - 3) ☒ deadlock detection
 - 4) - all of them